

I hear Tim is also Doing Γ -convergence of the Modica-Mortola Functional... (1)

We begin today by proving the last detail needed For

Γ -convergence of Cahn-Hilliard to the weighted Perimeter Functional.

Lemma: Let $A \subset \Omega$ be such that $\exists \tilde{A} \subset \mathbb{R}^N$ with

$\partial A = \partial \tilde{A} \cap \Omega$, $\partial \tilde{A}$ is a smooth C^1 manifold and
relative to Ω

$$\mathcal{H}^{N-1}(\partial \tilde{A} \cap \partial \Omega) = 0. \quad (\text{Transverse intersection})$$

Then for the distance function

$$d_A(x) := \begin{cases} \text{dist}(x, A^c) & x \in A \\ -\text{dist}(x, A) & x \in A^c \end{cases}$$

We have

$$\lim_{r \rightarrow 0} \mathcal{H}^{N-1}(\Omega \cap \{d_A = r\}) = \mathcal{H}^{N-1}(\partial A).$$

Proof: We begin by showing that the statement holds for $\Omega = \mathbb{R}^N$, i.e., $A = \tilde{A}$ a bounded set.

Arguing with the aid of a partition of unity we reduce to the local case that ∂A is given as the subgraph of a C^1 Lipschitz function. Precisely

$$A = \{x : x_N < g(x')\} \quad \text{for } g: \mathbb{R}^{N-1} \rightarrow \mathbb{R} \text{ a } C^1 \text{ function.}$$

Consider now $r \rightarrow 0$, ^{positive} we prove that

(2)

$$\mathcal{H}^{N-1}(Q[0, \pi] \cap \{d_A = r\}) \xrightarrow{r \rightarrow 0} \mathcal{H}^{N-1}(Q[0, \pi] \cap \partial A)$$

We represent $\{d_A = r\}$ as a graph.

For $v \in S^{N-1}$, $r \geq 0$, we define

$$g_{v,r}(x') = g(x' + rv) - rv_N$$



We define $g_r := \inf_{v \in S^{N-1}} \{g_{v,r}\}$, which is a Lipschitz function

by Arzela-Ascoli.

One can directly argue that $\{d_A = r\} = \text{Graph } g_r$

By the ~~Area~~ ^{Area} formula

$$\begin{aligned} & \mathcal{H}^{N-1}(Q[0, \pi] \cap \text{Graph } g_r) \\ &= \int_{Q[0, \pi]} \sqrt{1 + \| \nabla g_r \|^2} dx' \end{aligned}$$

Consequently our claim boils down to

(3)

$$\begin{aligned} \mathcal{H}^{N-1}(Q_{[0,T]} \cap \text{Graph } g_r) &= \int_{Q'} \sqrt{1 + \|\nabla g_r\|^2} dx' \\ &\rightarrow \int_{Q'} \sqrt{1 + \|\nabla g\|^2} dx' = \mathcal{H}^{N-1}(Q_{[0,T]} \cap \text{Graph } g) \\ &= \mathcal{H}^{N-1}(Q_{[0,T]} \cap \partial A) \end{aligned}$$

For this, we show that $\nabla g_r \rightarrow \nabla g$ in L^∞ .

By geometric considerations, $\nabla g_r(x') \in \text{Conv}_{v \in S^{N-1}} \{g_{v,r}(x')\}$
 $\subseteq \text{Conv}_{v \in B[0,r]} \{\nabla g(x'+v)\}$

Letting ω be the modulus of continuity for ∇g , it follows that

$$\|\nabla g_r(x') - \nabla g(x')\| \leq \omega(r)$$

and $\nabla g_r \rightarrow \nabla g$ in L^∞ , concluding the claim

(More Generally?)

To prove --- in general we argue as follows.

Define ~~the~~ $V_r = \{x \in \mathbb{R}^N : |d_A(x)| < r\}$

then $A_r = \tilde{A} \setminus V_r$ so that

$$\partial A_r = \{d_A = r\}.$$

Clearly $\chi_{A_r} \xrightarrow{L^1} \chi_A$ so that we can apply (4)

BV-LSC to find that

$$\begin{aligned} \mathcal{H}^{N-1}(\partial A) &= |D\chi_A|(\Omega) \leq \liminf_{r \rightarrow 0} |D\chi_{A_r}|(\Omega) \\ &\leq \liminf_{r \rightarrow 0} \mathcal{H}^{N-1}(\Omega \cap \{d_A = r\}) \end{aligned}$$

To prove the opposite claim, we have that

$$\mathcal{H}^{N-1}(\Omega \cap \{d_A = r\}) \leq \mathcal{H}^{N-1}(\partial A_r) - \mathcal{H}^{N-1}(\partial A_r \cap [\mathbb{R}^N \setminus \Omega])$$

$$\mathcal{H}^{N-1}(\Omega \cap \{d_A = r\}) \leq \mathcal{H}^{N-1}(\partial A_r) - \mathcal{H}^{N-1}(\partial A_r \cap [\mathbb{R}^N \setminus \Omega])$$

$$\begin{aligned} \text{Thus } \overline{\lim}_{r \rightarrow 0} \mathcal{H}^{N-1}(\Omega \cap \{d_A = r\}) &\leq \overline{\lim}_{r \rightarrow 0} |D\chi_{A_r}|(\Omega) \leq |D\chi_A|(\Omega) \\ &= \mathcal{H}^{N-1}(\Omega \cap \partial \tilde{A}) \\ &= \mathcal{H}^{N-1}(\partial A). \end{aligned}$$

With this we have properly concluded the proof that.

$$\int \frac{1}{\varepsilon} W(u_\varepsilon) + \varepsilon \|\nabla u_\varepsilon\|^2 \xrightarrow{\Gamma} C_0 \text{Per}[\cdot]$$

$$C_0 = \int_0^1 \sqrt{2W(s)} \, ds.$$

De Giorgi introduced Γ -convergence in '75

And first used in a related problem by Modica & Mortola in '77.

Using Γ -convergence, Modica '87 and Sternberg '88 proved

$$E_\varepsilon \xrightarrow{\Gamma} c_0 \text{Per}[\cdot] \quad (\text{up to modifications})$$

The reason this was essentially of interest was a conjecture by

M.E. Gurtin stating that ~~for~~ for minimizers u_ε of the energy E_ε ,

$$E_\varepsilon[u_\varepsilon] \sim \text{Per}[A], \quad \text{where}$$

$$\int \chi_A = \int u_\varepsilon \quad \text{and} \quad A \text{ minimizes the perimeter among}$$

fixed mass sets.

Given the Γ -convergence result, we know that $u_\varepsilon \rightarrow$ minimizer of $c_0 \text{Per}$

Consequently, $E_\varepsilon[u_\varepsilon] \rightarrow c_0 \text{Per}[A]$ as desired.

We now discuss a variety of related models

Example 1: Nonisothermal Phase Transition

(6)

Chemistry is dependent on temperature, and W is basically a mixing energy describing chemical incompatibility. It is natural for this relation to change for different temperatures, so

$$\int \frac{1}{\varepsilon} W(x, u) + \varepsilon \|\nabla u\|^2 \quad \text{is considered a}$$

nonisothermal model in the static setting. Well of W change with x .

This model has been studied by Gravina, Cristofori, Bouchitté, and in the context of vector valued homogenization by Fonseca, Cristofori, Grandi.

Example 2: Anisotropy of material.

For many crystals, there are preferred directions of orientation, and this is phenomenologically captured by the model

$$\int \frac{1}{\varepsilon} W(u) + \varepsilon \phi(\nabla u) dx, \quad \text{where}$$

in simple settings ϕ is basically $a\left(\frac{\nabla u}{\|\nabla u\|}\right) \|\nabla u\|^2$

Here the Γ -limit is given by

$$\int_{\partial^* A} a(v) d\mathcal{H}^{n-1}$$

Example 3: Multiphase

(7)

When there may be multiple phase that are ~~admissible~~ admissible in crystal growth, a natural associated energy is

$$\int \frac{1}{\varepsilon} W(u) + \varepsilon \|\nabla u\|^2 dx \quad \text{where } u: \Omega \rightarrow \mathbb{R}^d$$

is vector valued and W takes 0's on a compact set (think a finite number of choices). This was studied by (Fonseca, Tartar), (Baldo), (Ambrosio) when the Γ -limit is described in terms of a Caccioppoli partition.

Recently the dynamics of L^2 gradient flow have been shown to converge to multiphase MCF by (Larex and Simon '18).

Example 4: ~~Biological~~ Biological Membranes.

As proposed ~~for~~ for unilamellar membranes with phase separation, the energy

$$\int \frac{1}{\varepsilon} W(u) - g \varepsilon |\nabla u|^2 + \varepsilon^3 \|\nabla^2 u\|^2$$

is a local model describing phase separation. It Γ -converges to a perimeter functional, and a principal challenge is interpolation to control the middle term.

The original model is nonlocal, and is related to the Ohta-Kawasaki model for phase separation in diblock polymers

$$\int \frac{1}{\varepsilon} W(u) + \varepsilon \|\nabla u\|^2 + \iint_{\Omega \times \Omega} G(x,y) (u(x) - m) \cdot (u(y) - m) dx dy$$

See Zwickenagl and Collaborators.

(8)

Nonlocal Diffusion

Example 5 = Solid-Solid phase transitions

Let Ω be the ~~the~~ reference configuration of an elastic material and
 $u: \Omega \rightarrow \mathbb{R}^N$, $N=2,3$ the material displacement.

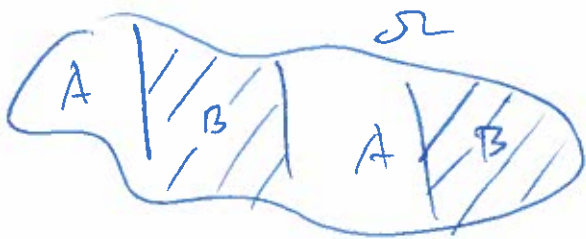
The energy $\int_{\Omega} \frac{1}{\epsilon} W(\nabla u) + \epsilon \|\nabla^2 u\|^2$ has been

used to model phase transitions in Solid-Materials.

For $W(S) = 0$ iff $S = A$ or B , to have nontrivial displacements in the limit, one must satisfy the compatibility.

$$A - B = \text{rank-one matrix} = a \otimes e, \quad a, e \in \mathbb{R}^N.$$

A classic result of Ball and James shows that for $\nabla u \in BU(\Omega; \mathbb{R}^N)$
and $\nabla u \in \{A, B\}$, $J_{\nabla u}$ consists of hyperplanes with normal
 e .



Generally things are in a frame invariant setting

Γ -convergence was proven by (Coti, Schweizer) see also (Tarola, Friedrich), (Shneor)

Connecting to evolution Problems

(9)

The L^2 gradient flow of E_ε is the Allen-Cahn equation

$$\partial_t u_\varepsilon = \Delta u_\varepsilon - \frac{W'(u_\varepsilon)}{\varepsilon^2}$$

$$\partial_\nu u_\varepsilon = 0$$

with the location of ε being movable by appropriate ^(dilations) scalings in time

For sufficiently smooth solutions u_ε , they can be characterized by the dissipation inequality:

$$E_\varepsilon[u_\varepsilon(T)] + \frac{1}{2} \int_0^T \varepsilon \|\partial_t u_\varepsilon\|_{L^2(\Omega)}^2 + \varepsilon \|\Delta u_\varepsilon - \frac{1}{\varepsilon^2} W'(u_\varepsilon)\|_{L^2(\Omega)}^2 dt \leq E_\varepsilon[u_\varepsilon(0)].$$

This is essentially

$$E_\varepsilon[T] + \frac{1}{2} \int_0^T \left[\|\partial_t u_\varepsilon\|_{X_\varepsilon}^2 + \|\nabla E_\varepsilon[u]\|_{X_\varepsilon}^2 \right] dt \leq E_\varepsilon[0]$$

Evolutionary Γ -convergence asks when is the above inequality stable as $\varepsilon \rightarrow 0$.
 $u_\varepsilon \rightarrow u$ and

$$\hookrightarrow E_0[T] + \frac{1}{2} \int_0^T \left[\|\partial_t u\|_{X_0}^2 + \|\nabla E_0[u]\|_{X_0}^2 \right] dt \leq E_0[0].$$

In the case of Allen-Cahn, one recovers Mean Curvature Flow.