Stability of networks

Motivation and Setting

Immediate reporting The determinist system

Summary and Outlook

On the stability of a dynamical system arising in telecommunication networks

Maite Wilke Berenguer

Technische Universität Berlin (RTG 1845)

Young Women in Probability 2014 Bonn, May 2014

▲□▶▲□▶▲□▶▲□▶ □ のQ@

Stability of networks

Motivation and Setting

Immediate reporting The deterministic system Simulations

Summary and Outlook

Motivation and Setting

Immediate reporting

• The deterministic system

▲□▶▲□▶▲□▶▲□▶ □ のQ@

Simulations



Summary and Outlook

Stability of networks

Motivation and Setting

"the last/first mile"





Aurzada; Scheutzow; Reisslein; and Maier (2010):

Towards a Fundamental Understanding of the Stability and Delay of Offline WDM FPONs. IEEE/OSA Journal of Optical Communications and Networking, 2, 51-66

▲□▶▲□▶▲□▶▲□▶ □ のQ@

Setting



МWВ

Motivation and Setting

Immediate reporting The deterministi system Simulations

Summary and Outlook



Setting



Poisson arrivals with parameter λ > 0 [bits / s]

▲□▶▲□▶▲□▶▲□▶ □ のQ@

• channel capacity *C* = 1 [bits / s]

Setting



▲□▶▲□▶▲□▶▲□▶ □ のQ@

• channel capacity *C* = 1 [bits / s]

normalised traffic load $\rho := \frac{\lambda}{C} = \lambda$



MWB

Motivation and Setting

Immediate reporting The deterministic system Simulations

Summary and Outlook





M W B

Motivation and Setting

Immediate reporting The deterministic system Simulations

Summary and Outlook



◆□▶ ◆□▶ ◆臣▶ ◆臣▶ ─臣 ─のへで

● ONUs send report (区) to OLT



МWВ

Motivation and Setting

Immediate reporting The deterministic system Simulations

Summary and Outlook



- ONUs send report (区) to OLT
- OLT sends grant to ONUs (largest-processing-time-first schedule)

▲□▶▲□▶▲□▶▲□▶ □ のQ@



Motivation and Setting

Immediate reporting The deterministic system Simulations

Summary and Outlook



- ONUs send report (区) to OLT
- OLT sends grant to ONUs (largest-processing-time-first schedule)

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

• ONUs send all packets reported while new packets arrive



МWВ

Motivation and Setting

Immediate reporting The deterministic system Simulations

Summary and Outlook



- ONUs send report (区) to OLT
- OLT sends grant to ONUs (largest-processing-time-first schedule)

▲□▶▲□▶▲□▶▲□▶ □ のQ@

• ONUs send all packets reported while new packets arrive



МWВ

Motivation and Setting

Immediate reporting The deterministic system Simulations

Summary and Outlook



- ONUs send report (区) to OLT
- OLT sends grant to ONUs (largest-processing-time-first schedule)
- ONUs send all packets reported while new packets arrive
- ONUs send new report to OLT



Motivation and Setting

Immediate reporting The deterministic system Simulations

Summary and Outlook



- ONUs send report (区) to OLT
- OLT sends grant to ONUs (largest-processing-time-first schedule)

▲□▶▲□▶▲□▶▲□▶ □ のQ@

- ONUs send all packets reported while new packets arrive
- ONUs send new report to OLT

Stability of networks

МWВ

Motivation and Setting

Immediate reporting The deterministic system Simulations

Summary and Outlook

synchronized reporting



- ONUs send report (区) to OLT
- OLT sends grant to ONUs (largest-processing-time-first schedule)

・ロット (雪) (日) (日)

э

- ONUs send all packets reported while new packets arrive
- ONUs send new report to OLT

 Q_n^i : duration of the *n*th transmission of *i*th ONU



МWВ

Motivation and Setting

Immediate reporting

The deterministic system Simulations

Summary and Outlook

	Q_{n-1}^{1}		Q_n^3		chernel
	Q_{n-1}^2	Q_{n-1}^{3}	Q_n^2	Q_n^1	occupancy



МWВ

Motivation and Setting

Immediate reporting

The deterministic system Simulations

Summary and Outlook





МWВ

Motivation and Setting

Immediate reporting

The deterministic system Simulations

Summary and Outlook



◆□▶ ◆□▶ ◆臣▶ ◆臣▶ ─臣 ─のへで

ONU 1 -



МWВ

Motivation and Setting

Immediate reporting

The deterministic system Simulations

Summary and Outlook







Motivation and Setting

Immediate reporting

The deterministic system Simulations

Summary and Outlook







МWВ

Motivation and Setting

Immediate reporting

The deterministic system Simulations

Summary and Outlook







MWB

Motivation and Setting

Immediate reporting

The deterministic system Simulations

Summary and Outlook





 $-Q_{n-1}^{1}+Q_{n-1}^{2}+Q_{n-1}^{3}+2\tau+Q_{n}^{1}+Q_{n}^{2}$





$$\begin{split} &-Q_{n-1}^1+Q_{n-1}^2+Q_{n-1}^3+2\tau+Q_n^1+Q_n^2\\ \Rightarrow Q_{n+1}^1\sim \mathsf{Poi}(\rho(-Q_{n-1}^1+Q_{n-1}^2+Q_{n-1}^3+2\tau+Q_n^1+Q_n^2)) \end{split}$$



▲□▶▲□▶▲□▶▲□▶ □ のQ@





< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □



< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □



$$ar{Q}_{n+1} \sim \mathsf{Poi}\left(
ho\left(\textit{A}_{n+1}ar{\textit{Q}}_{n-1} + \textit{B}_{n+1}ar{\textit{Q}}_n + 2ar{ au}
ight)
ight)$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ



$$ar{Q}_{n+1} \sim \mathsf{Poi}\left(
ho\left(A_{n+1}ar{Q}_{n-1} + B_{n+1}ar{Q}_n + 2ar{ au}
ight)
ight)$$

▲□▶▲□▶▲□▶▲□▶ □ のQ@

What is the critical value ρ_c ?



Motivation and Setting

Immediate reporting

The deterministic system Simulations

Summary and Outlook



$$ar{Q}_{n+1} \sim ext{Poi}\left(
ho\left(\textit{A}_{n+1}ar{\textit{Q}}_{n-1}+\textit{B}_{n+1}ar{\textit{Q}}_n+2ar{ au}
ight)
ight)$$

▲□▶▲□▶▲□▶▲□▶ □ のQ@

What is the critical value ρ_c ?

expect: $\rho_c = \frac{1}{2}$



МWВ

Motivation and Setting

Immediate reporting

The deterministic system Simulations

Summary and Outlook



$$ar{Q}_{n+1} \sim ext{Poi}\left(
ho\left(\textit{A}_{n+1}ar{\textit{Q}}_{n-1}+\textit{B}_{n+1}ar{\textit{Q}}_n+2ar{ au}
ight)
ight)$$

▲□▶▲□▶▲□▶▲□▶ □ のQ@

What is the critical value ρ_c ?

expect: $\rho_c = \frac{1}{2}$

simulations suggest: $\rho_c = \frac{1}{\sqrt{3}}$

Stability of networks

Motivation and

Setting

Immediate reporting

The deterministic system

Summary and Outlook

Bassir (2010)

Stabilitätsanalyse eines dynamischen Systems aus der Nachrichtentechnik: WDM EPONs, *Diplomarbeit (TU Berlin)*

$$ar{m{Q}}_{n+1}\sim {\sf Poi}\left(
ho\left(m{A}_{n+1}ar{m{Q}}_{n-1}+m{B}_{n+1}ar{m{Q}}_n+2ar{ au}
ight)
ight)$$

$$ar{q}_{n+1} =
ho \left(a_{n+1} ar{q}_{n-1} + b_{n+1} ar{q}_n + 2ar{ au}
ight)$$

▲□▶▲□▶▲□▶▲□▶ □ のQ@



Motivation and Setting

Immediate reporting

The deterministic system

Summary and Outlook





イロト 不得 トイヨト イヨト

= 900



Motivation and Setting

Immediate reporting

The deterministic system

Summary and Outlook

$$\bar{q}_{n+1} = \rho \left(a_{n+1} \bar{q}_{n-1} + b_{n+1} \bar{q}_n + 2\bar{\tau} \right)$$



▲□▶▲□▶▲□▶▲□▶ □ のQ@

Stability of networks



◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへぐ

simulations: an explanation

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Stability of networks

Motivation and Setting

Immediate reporting

system Simulations

Summary and

Code: courtesy of Frank Aurzada.

)
$$Q_n^1 + Q_n^2 + Q_n^3$$



simulations: an explanation


$\left|\frac{1}{2}\right| < \rho < \rho_{\alpha} = \frac{1}{\sqrt{3}}$



 $\frac{1}{2} < \rho < \rho_{\alpha} = \frac{1}{\sqrt{3}}$



. . .

Motivation and Setting

Immediate reporting The determinis

system

Summary and Outlook



 $\frac{1}{2} < \rho < \rho_{\alpha} = \frac{1}{\sqrt{3}}$



Motivation and Setting

Immediate reporting The determinis

Simulations

Summary and Outlook



 $\frac{1}{\sqrt{3}} = \rho_{\alpha} < \rho < \rho_{\beta}$



イロト イロ・イモト イモト モーシンへの

 $\frac{1}{\sqrt{3}} = \rho_{\alpha} < \rho < \rho_{\beta}$

Stability of networks

мwв

Motivation and Setting

Immediate reporting The determinis

system Simulations

Summary and Outlook



 $\frac{1}{\sqrt{3}} = \rho_{\alpha} < \rho < \rho_{\beta}$



MWB

Motivation and Setting

Immediate reporting The determinis

system Simulations

Summary and Outlook



To take home:

Stability of networks

Motivation and Setting

Immediate reporting The deterministi system

Summary and Outlook

$$ar{Q}_{n+1} \sim \mathsf{Poi}\left(
ho\left(m{A}_{n+1}ar{Q}_{n-1} + m{B}_{n+1}ar{Q}_n + 2ar{ au}
ight)
ight)$$

▲□▶▲□▶▲□▶▲□▶ □ のQ@

Critical value $\rho_c = \frac{1}{\sqrt{3}}$ is larger than expected, since **distinct** waiting times can fall into stabilizing pattern for N = 3 and M = 2!



ONU 3 🖷 🚽

To take home:

Stability of networks

Motivation and Setting

Immediate reporting The deterministi system

Summary and Outlook

$$ar{Q}_{n+1} \sim \mathsf{Poi}\left(
ho\left(\mathcal{A}_{n+1}ar{Q}_{n-1} + \mathcal{B}_{n+1}ar{Q}_n + 2ar{ au}
ight)
ight)$$

Critical value $\rho_c = \frac{1}{\sqrt{3}}$ is larger than expected, since **distinct** waiting times can fall into stabilizing pattern for N = 3 and M = 2!



< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

To take home:

Stability of networks

Motivation and Setting

Immediate reporting The deterministic system Simulations

Summary and Outlook



Critical value $\rho_c = \frac{1}{\sqrt{3}}$ is larger than expected, since **distinct** waiting times can fall into stabilizing pattern for N = 3 and M = 2!





< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

Outlook

Stability of networks

Motivation and Setting

Immediate reporting The deterministic system Simulations

Summary and Outlook To do:

- $\rho_{\rm C} = \frac{1}{\sqrt{3}}$
- characterisation and analysis of $\frac{1}{\sqrt{3}} \leq \rho \leq \rho_{\beta}$
- limiting properties of the invariant distribution for $\rho \rightarrow \frac{1}{\sqrt{3}}$

< □ > < 同 > < 三 > < 三 > < 三 > < ○ < ○ </p>

• rate, delay ...

Stability of networks

Motivation and Setting

Immediate reporting The determinist system Simulations

Summary and Outlook

THANK YOU!

◆□ > ◆□ > ◆ 三 > ◆ 三 > ● ○ ○ ○ ○

Stability of networks

Motivation and

Immediate reporting The deterministi system Simulations

Summary and Outlook

 $ar{Q}_{n+1} \sim \mathsf{Poi}\left(
ho\left(A_{n+1}ar{Q}_{n-1} + B_{n+1}ar{Q}_n + 2ar{ au}
ight)
ight)$

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへぐ

Stability of networks

Motivation and Setting

Immediate reporting The deterministi system Simulations

Summary and Outlook

$$ar{Q}_{n+1} \sim \mathsf{Poi}\left(
ho\left(m{A}_{n+1}ar{Q}_{n-1} + m{B}_{n+1}ar{Q}_n + 2ar{ au}
ight)
ight)$$

Set $\tilde{Q}_n := \left(\bar{Q}_n, \bar{Q}_{n-1}\right)^T$ (markovian) and rewrite

$$ilde{Q}_{n+1} = D_{
ho,n} ilde{Q}_n + ext{"error"}(ilde{Q}_n)$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Stability of networks

Motivation and Setting

Immediate reporting The deterministic system Simulations

Summary and Outlook

$$ar{Q}_{n+1}\sim extsf{Poi}\left(
ho\left(oldsymbol{A}_{n+1}ar{Q}_{n-1}+oldsymbol{B}_{n+1}ar{Q}_n+2ar{ au}
ight)
ight)$$

Set $\tilde{Q}_n := (\bar{Q}_n, \bar{Q}_{n-1})^T$ (markovian) and rewrite

$$ilde{Q}_{n+1} = D_{
ho,n} ilde{Q}_n + ext{"error"}(ilde{Q}_n)$$

 A_n and B_n (thus also $D_{\rho,n}$) only depend on "order" of Q^1, Q^2, Q^3 !

▲□▶▲□▶▲□▶▲□▶ □ のQ@

Stability of networks

Motivation and Setting

Immediate reporting The deterministic system Simulations

Summary and Outlook

$$ar{Q}_{n+1}\sim extsf{Poi}\left(
ho\left(oldsymbol{A}_{n+1}ar{Q}_{n-1}+oldsymbol{B}_{n+1}ar{Q}_n+2ar{ au}
ight)
ight)$$

Set $\tilde{Q}_n := \left(\bar{Q}_n, \bar{Q}_{n-1}\right)^T$ (markovian) and rewrite

$$ilde{Q}_{n+1} = D_{
ho,n} ilde{Q}_n + ext{"error"}(ilde{Q}_n)$$

 A_n and B_n (thus also $D_{\rho,n}$) only depend on "order" of Q^1, Q^2, Q^3 !

Now consider " $X_n := \operatorname{sort}(\tilde{Q}_n)$ " on a pattern



▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

Stability of networks

Motivation and Setting

Immediate reporting The deterministic system Simulations

Summary and Outlook

$$ar{Q}_{n+1}\sim extsf{Poi}\left(
ho\left(oldsymbol{A}_{n+1}ar{Q}_{n-1}+oldsymbol{B}_{n+1}ar{Q}_n+2ar{ au}
ight)
ight)$$

Set $\tilde{Q}_n := \left(\bar{Q}_n, \bar{Q}_{n-1}\right)^T$ (markovian) and rewrite

$$ilde{Q}_{n+1} = D_{
ho,n} ilde{Q}_n + ext{"error"}(ilde{Q}_n)$$

 A_n and B_n (thus also $D_{\rho,n}$) only depend on "order" of Q^1, Q^2, Q^3 !

Now consider " $X_n := \operatorname{sort}(\tilde{Q}_n)$ " on a pattern

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

$$X_{n+1}=C_{\rho}X_n+\xi_{n+1}(X_n,.)$$

 $\left|\frac{1}{2}\right| < \rho = \frac{1}{\sqrt{3}}$



 $\frac{1}{2} < \rho < \rho_{\alpha} = \frac{1}{\sqrt{3}}$



Motivation and Setting

Immediate reporting The deterministi system

Summary and Outlook



., 2 P

long simulation



· , 2 @

long simulation



Motivation and Setting

Immediate reporting The deterministi system Simulations

Summary and Outlook



same scale stable cases



same scale stable cases



another $\rho_{\alpha} < \rho < \rho_{\beta}$



another $\rho_{\alpha} < \rho < \overline{\rho_{\beta}}$



another $\rho_{\alpha} < \rho < \rho_{\beta}$



Stability of

Summary and Outlook



 $\rho < \frac{1}{2} < \rho_{\alpha} = \frac{1}{\sqrt{3}}$



Motivation and Setting

Immediate reporting The deterministi system Simulations

Summary and Outlook



.,20

 $\rho_{\beta} < \rho$

Stability of networks

Motivation and Setting

Immediate reporting The deterministi system Simulations

Summary and Outlook



.,20

the deterministic model

Stability of networks

MWB

Motivation and Setting

Immediate reporting The determinis system

Summary and Outlook $\rightsquigarrow \hat{x}_{n+1} = C^{\alpha,\beta} \hat{x}_n + \hat{\tau}$

the deterministic model

Stability of networks

Motivation and Setting

Immediate reporting The determinis system Simulations

Summary and Outlook

$$\rightsquigarrow \hat{x}_{n+1} = C^{\alpha,\beta} \hat{x}_n + \hat{\tau}$$

▲□▶▲□▶▲□▶▲□▶ □ のQ@

Let λ_{α} , λ_{β} be the largest eigenvalue of C_{α} , resp. C_{β} .

the deterministic model

Stability of networks

Motivation and Setting

Immediate reporting The deterministi system Simulations

Summary and Outlook

$$\rightsquigarrow \hat{X}_{n+1} = C^{\alpha,\beta} \hat{X}_n + \hat{\tau}$$

Let λ_{α} , λ_{β} be the largest eigenvalue of C_{α} , resp. C_{β} .

$$\lambda_{\alpha} \begin{cases} < \\ = \\ > \end{cases} \mathbf{1} \Leftrightarrow \rho \begin{cases} < \\ = \\ > \end{cases} \frac{1}{\sqrt{3}} \qquad \qquad \lambda_{\beta} \begin{cases} < \\ = \\ > \end{cases} \mathbf{1} \Leftrightarrow \rho \begin{cases} < \\ = \\ > \end{cases} \rho \ast$$

▲□▶▲□▶▲□▶▲□▶ □ のQ@

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ ─臣 ─のへで

Stability of networks

Motivation and Setting

Immediate reporting The deterministi system Simulations

Summary and Outlook

1 $Q_n^1 + Q_n^2 + Q_n^3$

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ─ □ ─ の < @

Stability of networks

Motivation and Setting

Immediate reporting The deterministic system

Summary and Outlook





Stability of networks

Motivation and Setting

Immediate reporting The deterministic system

Summary and Outlook







▲□▶ ▲□▶ ▲□▶ ▲□▶ = 三 のへで

Stability of networks

Motivation and Setting

Immediate reporting The deterministic system

Summary and Outlook







▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

Stability of networks

Motivation and Setting

Immediate reporting The deterministic system

Summary and Outlook







▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ



Motivation and Setting

Immediate reporting The deterministisystem Simulations

Summary and Outlook


simulations: a detailed explanation



simulations: a detailed explanation

